# Optimizing Outdoor Propagation Model based on Measurements for Multiple RF Cell

Allam Mousa
Department of Electrical
Engineering
An-Najah National
University, Nablus,
Palestine.

Yousef Dama
Department of Electrical
Engineering
An-Najah National
University, Nablus,
Palestine.

Mahmoud Najjar
Department of Electrical
Engineering
An-Najah National University,
Nablus,
Palestine.

Bashar Alsayeh
Department of Electrical
Engineering
An-Najah National
University, Nablus,
Palestine.

#### **ABSTRACT**

This paper intends to study outdoor RF attenuation path loss behavior under certain restrictions. The study has been conducted in Nablus city to develop and optimize a suitable propagation model based on one of the existing propagation models based on outdoor measurements for 900 MHz, where a local GSM system is operating under sever geographical terrains and frequency limitations. The optimized model has been chosen such that certain error parameters are minimized. Some of the proposed models are; Bertoni-Walfish, Hat, Walfisch-Ikegami and the standard macrocell. In this paper a Tuned Bertoni-Walfisch model has outperformed the other models and has proven, to be the best suited for propagation analysis involving such terrain. This is achieved by varying the range dependence using *Least Mean Square Error* (LMSE) method

#### **Keywords**

Multipath channel, radio channel modeling, Path loss model, Propagation measurements, Bertoni-Walfisch model, GSM 900.

### 1. INTRODUCTION

Propagation, or path loss, models are basically used to predict coverage area, frequency assignment and interference, which are the main concerns in cellular network planning. The generalization of these models, to any environment, is suitable for either particular areas (urban, suburbs and rural), or specific cell radius (macrocell, microcell, picocell) depending diversity of environment where communications occur. In general, there is a relationship between these models and types of environments for which they are suitable. The models can be any of the three types, namely the empirical modes (like Okumora and Hata models), semi-empirical models (like Cost-231 and Walfish-Ikegami models) and deterministic models (Maxwell's Eq.) which are site specific and require enormous number of geometry information about the location. The empirical models' parameters can be adjusted or tuned according to a targeted environment. The propagation model tuning must optimize the model parameters in order to achieve minimal error between predicted and measured signal strength. This will make the model more accurate for received signal predictions

Usually, operators use special planning software like ASSET and ATOLL, to accomplish propagation model tuning [1], [2]. A Palestinian mobile communication operator, which operates

at GSM900, uses ASSET software which uses Standard Macrocell model, based on modified Hata model.

# 2. Terrestrial description of Nablus city and Survey Analyses

The city of Nablus cast narrow streets and moderately high buildings, the buildings heights vary between 9 and 12 m within the old city and city center Most of the buildings are mass of concrete, rock-like blocks, and bricks

The city is surrounded by two mountains from north with approximate height of 950 m and from the south with approximate height of 881 m and they are separated by around 2 km.

Extensive experimental tests were performed in the geographic area of Nablus and especially in the city center. The aim of these tests was to investigate the RF propagation in different directions relative to the streets. The results of those measurements were used to define the standard deviation, mean and RMSE, such that these values will be used to obtain a better understanding of wave propagation in the city.

In this section, the steps of collecting measurements, the equipment used and the statistical analyses of the measurements are presented. The main idea of the statistical analyses is to understand the radio wave propagation behavior for Nablus city at 900 MHz and finally to compare them with the applicable propagation models.

The data measurement equipments consist of a laptop equipped with TEMS software, a test mobile phone and a Global Positioning system (GPS). This tool can measure data in real time which can provide information about the network performance.

According to the requirement of radio network planning a single macrocell base station has been chosen to start with. The station is located in down town; the drive test has been performed walking through each lane to cover the entire area from the northern mountain through the city center to the southern one. Unfortunately, this test had failed since the frequency of the selected cell had been reused repeatedly. So, we received the signal just around 200 meters as a maximum distance due to interference with other neighboring cells, which is not enough to make a useful analysis. As a result, we cannot conclude a clear relationship between distance and path loss slope per decade.

Due to a last fail test, we need to repeat this test with the same cell. But at this time, we turned off the neighboring 6 cells which have the same frequency at midnight. Where we cannot turning off the cells during day, because cells are busy so the most of capacity of cells are full enough. So, the number of samples became larger and the range of distance is wider. The received power ranges from -35 dBm to -120 dBm with distance ranges between 4 m and 521 m with 50748 samples. The specifications of the tested base station are illustrated in Table 1.

Table 1: Macrocell information.

Antenna Name	XPol A-Panel 806–960 12.5dBi		
Type No.	739 620		
Channel No. (BCCH)	111		
Frequency (BCCH)	957.2 MHz		
PTX	45 dBm		
GTX	2 x 12.5 dBi		
EIRP	48.9 dBm		
Azimuth	120o		
Height	12 m		
Down tilt (total)	10o		
Feeder length	15 m		

The measured values of the received signal strength are illustrated in Fig. 1.

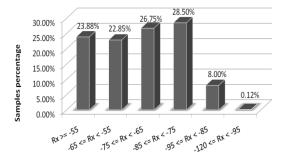


Fig.1: Received power distribution for BS1.

Received power ranges

The coverage prediction map of Standard macrocell model based in Hata model using ASSET software with received power (dBm) sampling is shown in Fig.2

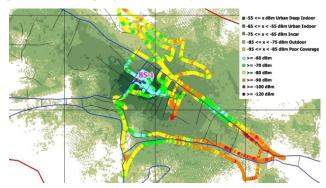


Fig.2: Prediction map of BS1 for ASSET software and drive test samples.

#### 3. PROPAGATION MODELS

#### 3.1 Standard Macrocell model

The Standard Macrocell model incorporates an optimal dual slope loss model with respect to distance from the base station. It also incorporates algorithms for effective base station heights, diffraction loss, and the effects of clutter. The general path loss (PL) formula for the Macrocell models is as follows [7];

$$Path \ Loss(dB) = k_1 + k_2 \log(d) + k_3(H_{ms}) + k_4 \log(H_{ms}) + k_5 \log(H_{eff}) + k_6 \log(H_{eff}) \log(d) + k_7(diffin) + C_{loss}$$
 (1)

Where: d is the distance from the base station to the mobile station (km);  $H_{ms}$  is the height of the mobile station above ground (m);  $H_{eff}$  is the effective base station antenna height (m); diffn is the diffraction loss calculated using either the Epstein-Peterson, Bullington, Deygout or Japanese Atlas knife edge techniques;  $k_1$  and  $k_2$  are intercept and slope. These factors correspond to a constant offset (in dB) and a multiplying factor for the log of the distance between the base station and mobile;  $k_3$  is mobile Antenna Height Factor. Correction factor used to take into account the effective mobile antenna height;  $k_4$  is multiplying factor for  $H_{ms}$ ;  $k_5$  is Effective Antenna Height Gain. This is the multiplying factor for the log of the effective antenna height;  $k_6$  is the multiplying factor for log  $(H_{eff})\log(d)$ ;  $k_7$  is the multiplying factor for diffraction loss calculation; C\_loss is the clutter specifications taken into account in the calculation process.

The propagation model can be tuned by modifying the k-factors. For improved near and far performance, dual slope attenuation can be introduced by specifying both near and far values for  $k_1$  and  $k_2$ , and the crossover point.

### 3.2 Log-distance propagation model

The Log – distance propagation model is based on the theory that; the average received signal power decreases logarithmically with distance (d) between the transmitter and the receiver [8-9]. This can be expressed as;

$$PL(dB) = L_o + 10n\log(d/d_o)$$
 (2)

Where,  $L_0$ =32.4+20log<sub>10</sub>(f)+20log<sub>10</sub>(d<sub>o</sub>) is the reference path loss, n is the path loss exponent (usually empirically determined by filed measurement), d0 is the reference distance in (km), d is the distance between transmitter and receiver in (km). Table 2 gives some typical values of n, larger values of n correspond to more obstructions and hence faster decreases in average received power as distance becomes larger [8].

It is important to select a free space reference distance that is appropriate for the propagation environment. In large coverage cellular systems, 1 km reference distances are commonly used, whereas in microcellular systems, much smaller distances (such as 100 m or 1 m) are used. The reference distance should always be in the far field of the antenna so that near-field effects do not alter the reference path loss [8-10].

Table 2: Path Loss Exponents for Different Environments

Environment	Path Loss Exponent , n
In building line-of-sight	1.6 to 1.8
Free Space	2
Obstructed in factories	2 to 3
Urban area cellular radio	2.7 to 3.5
Shadowed urban cellular radio	3 to 5
Obstructed in building	4 to 6

This model implementation may be achieved by Choosing d0 = 1 (m) as a reference, one may apply this model to measure and calculate the path loss exponent n (Eq.2). This value is found to be 3.86 which mean that BS1 is located in shadowed urban area as discussed in Table 2. Hence, the Log-distance propagation model may be re-written as;

$$PL(dB) = L_o + 38.6 \log \left(\frac{d}{d_o}\right)$$
 (3)

The Simulation results for this propagation model and the measured values are illustrated in Fig. 3. Moreover, applying this model for other cells to find path loss exponent n is illustrated in Table 3, where the main statistical indications (Mean Error  $\mu$ , Standard Deviation  $\sigma$ , Root Mean Square Error (RMSE)) for Log-distance propagation model values compared to the measured ones are illustrated in Table 4.

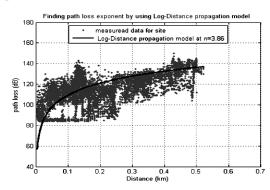


Fig.3: Log-distance model at n=3.86 and measured data.

Table 3: Path loss exponent for different base stations.

Cell No.	1	2	3	4	5	6	7	8
Path	3.86	3.9	3.6	3.82	4.16	3.64	3.91	4.41
Loss								
exponent								
(n)								

Table 4: Statistical values for Log-distance propagation model applied for certain base stations.

Base station No.	# of samples	Mean error	Standard deviation	RMSE
BS1	50748	2.11	13.14	13.31
BS2	4163	2.22	13.864	14.04
BS3	9627	0.22	8.8	8.8116
BS4	8336	0.72	11.396	11.4186
BS5	21390	1.473	11.628	11.721
BS6	3968	0.1547	5.9	5.92
BS7	3937	0.444	9.414	9.423
BS8	2652	0.335	9.06	9.065

Table 3 indicates typical n values referring to all base stations located in shadowed urban area which is true as discussed in Table 2.

### 3.3 Bertoni-Walfisch propagation model

Bertoni-Walfisch proposed a semi empirical model that is applicable to propagation though buildings in urban environments. Which, it has been adopted here due to its simplicity and validity which has been verified with measurements [10]. The model assumes building heights to be uniformly distributed and the separation between buildings are equal. Propagation is then equated to the process of multiple-diffraction past these rows of buildings. The building geometry and parameters in Bertoni-Walfisch model are illustrated in Fig. 4.

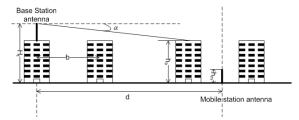


Fig.4: The building geometry and parameters in Bertoni-Walfisch Model.

The path loss formula for Bertoni-Walfisch propagation Model is given as [3], [4];

$$PL(dB) = 89.5 + A + 38\log(d) - 18\log(h_t - h_h) + 2\log(f)$$
 (4)

Where

$$A = 5\log\left(\frac{b}{2}\right)^{2} + (h_{b} - h_{m}) - 9\log(b) + 20\log\left\{\tan^{-1}\left[\frac{2(h_{b} - h_{m})}{b}\right]\right\}$$

d: Distance between base station and the mobile in km.

f :Frequency in MHz

 $h_t$ : Antenna Height in meters.

 $h_b$ : Building height in meters.

 $h_m$ : Mobile height in meters.

b :center-to-center spacing of the rows of the buildings in meters

In propagation studies, there are many propagation models especially in urban areas like (Hata, Haret, COST231 Walfisch-Ikegami, and Bertoni-Walfisch) [8], to choose the most accurate one, we applied many of them to compar the performance with the measured data (BS1) then we made a comparison between them to check which one has a minimum error. Some of the statistical indicators are illustrated in Table 5 for the widely used propagation models.

Table 5: Mean error, standard deviation and RMSE for various models for BS1.

Empirical Propagation model	Mean error (dB)	Stand ard devia tion	RMS E	
Hata	12.598	12.96	18.07 5	
Haret	10.348	12.98	16.6	
COST231 Walfisch- Ikegami	10.58	12.99	16.76	
Bertoni- Walfisch	1.426	13	13.07	

From Table 5, one can notice that Bertoni-Walfisch is the best model, under our circumstances, since it has the minimum mean error and minimum RMSE. Hence, in order to improve the performance of this model (increase its accuracy), it is aimed to tune it using certain techniques like Least Mean Square Error (LMSE).

# 4. OPTIMIZATION PROCESS

The optimization, or tuning, process is based on the measured data using least square method. Statistical analysis such as mean error, standard deviation and root mean error were used. Comparison between optimized model and other models were compared according to these statistical values. An illustrative block diagram is shown in Fig.5 [11].

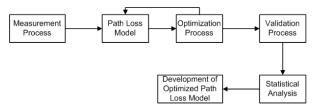


Fig.5: Block diagram of optimization process.

# 4.1 STANDARD MACROCELL MODEL TUNING

The Standard Macrocell model has been tuned by applying LMSE on the path loss equation given in Eq.1, the tuned model can be written as;

$$PL(dB) = 139.41 + 30\log(d) - 2.55(H_{mS}) + 0\log(H_{mS})$$

$$-13.82\log(H_{eff}) - 6.55\log(H_{eff})\log(d) + 0.7(d_{iffn}) + C_{Loss}$$
(5)

The k factors of the model were tuned such that the obtained values for k1 and k2 are 139.41 and 30 respectively to replace the unturned values of 135 and 38, the values of k3 - k7 remains unchanged as shown in Table 6.

Table 6: Model parameters before and after tuning

Parameters	Before tuning	After tuning		
k1	135	139.41		
k2	38	30		
k3	-2.55			
k4	0			
k5	-13.82			
k6	-6.55			
k7	0.7			

The path loss of measured data and Macrocell model before tuning versus tuned model is shown in Fig.6. The tuned model represents the measured data with less mean error.

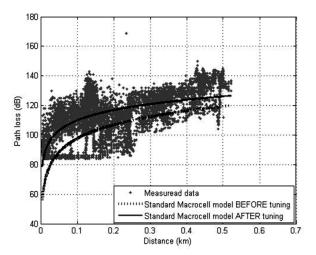


Fig.5: Path loss comparison of Standard macrocell model before and after tuning for BS1.

# 4.2 BERTONI-WALFISCH MODEL TUNING

Optimization of the Bertoni-walfisch Model is based on minimizing the LMSE between the best fit of the model and the practically measured data as given in Eq. 6 [11].

$$\sum_{i=1}^{N} [y_i - E_R(x_i, a, b, c, ...)] = \min$$
(6)

 $y_i$  = measurement result at the distance  $x_i$ .  $E_R(xi; a; b; c;)$  = modeling result at the  $x_i$  based on optimization.

a; b; c = parameter of the model based on optimization; n = Number of the experiment data set.

Accordingly, the tuned Bertoni-Walfisch model is tuned to;

$$PL(dB) = 78.5 + A + 23\log(d) - 18\log(h_t - h_b) + 21\log(f)$$
 (7)

Based on the Bertoni-Walfisch model, the Simulation results are illustrated for the original and tuned model in terms of path loss as shown in Fig. 7. From Eq. (7), one can see that, the path loss increases with distance at a rate of 23 dB per decade in Bertoni-Walfisch model after tuning.

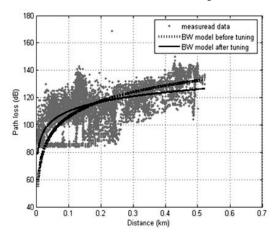


Fig. 7: Path loss comparison of Bertoni-Walfisch model before and after tuning.

The statistical analysis calculated were for the merits of Mean error  $\mu$ , Standard deviation  $\sigma$  and Root Mean Square Error (RMSE) [12], [13], [14]. Where, error is the difference between measured and predicted values of tuned Bertoni-Walfisch model. The results of the statistical analysis for Bertoni-Walfisch model and Standard Macrocell model are given in the Table 7.

Table 7 Mean error, standard deviation and RMSE comparison for Bertoni-Walfisch and Standard Macrocell models

	μ (dB)		Σ	Σ		RMSE	
	Before tuning	After tuning	Before tuning	After tuning	Before tuning	After tuning	
Bertoni- Walfisch	1.426	0	13	11.294	13.07	11.294	
Standard Macrocell model	10.91	0	11.792	11.294	16.06	11.294	

#### 5. Simulation and Results

The tuned Bertoni-walfisch model has been applied for 8 base stations in Nablus. Where, multiple cell implementations have been conducted. The performance has been compared to several other models like Hata, Walfish-Ikegami, Hata and standard Macrocell. Comparison has been performed in terms of error and standard deviation as shown in Table 8 and Table 9 respectively. The comparison shows that the proposed tuned Bertoni-Walfisch tuned model is suitable for almost all the base stations since the error was reduced significantly. The proposed tuned model has been compared to other models as shown in Fig.8. The mean error of BS1 has been reduced to zero and the standard deviation was decreased by 13.12% and the average standard deviation is 8.47.

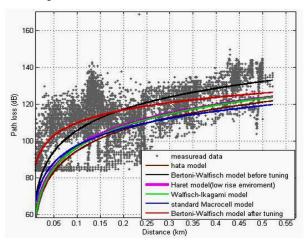


Fig.8: Path loss comparison between measured data for BS 1 and propagation models.

Table 8: Mean Error comparison between tuned Bertoni-Walfisch models with known models

BS#	Tuned Bertoni - Walfisc h	Bertoni - Walfisc h	Hata	Walfisch - Ikegami	Haret	Standar d Macroce ll model
BS1	0	1.426	12.59 8	10.58	10.34 8	10.91
BS2	6.978	10.728	17.82	16.5	10.32 9	18.536
BS3	2.367	9.633	9.737	10.106	8.636	12.067
BS4	3.254	6.941	14.72	11.697	10.96	14.510

			6		6	
BS5	13.041	12.32	23.11 7	18.936	15.76 9	21.774
BS6	3.342	11.576	10.78 9	11.083	9.707	13.565
BS7	5.88	8.891	16.42 4	14.322	13.56 7	16.797
BS8	16.813	16.311	27.21 4	25.255	24.37 7	25.971
Averag e Mean Error	6.64	9.55	16.55	14.80	12.96	16.76

Table 9: Standard Deviation comparison for tuned Bertoni-Walfisch model with known models

BS#	Tuned Bertoni - Walfisc h	Bertoni - Walfisc h	Hata	Walfisc h- Ikegami	Hare t	Standar d Macroce ll model
BS1	11.294	13	12.96	12.99	12.98	11.792
BS2	9.544	13.52	12.73 2	13.52	12.87 9	10.807
BS3	7.956	8.941	8.861	8.94	12.35 8	8.396
BS4	9.2	11.362	11.16 3	11.362	11.36 2	10.157
BS5	9.09	10.987	10.56 7	10.987	10.64 4	9.621
BS6	5.127	6.027	5.944	6.026	5.924	5.496
BS7	8.039	9.286	9.220	9.286	9.229	8.556
BS8	7.559	8.538	8.489	8.538	8.496	7.987
Average Standard Deviatio n	8.47	10.20	9.99	10.20	10.48	9.10

### 6. CONCLUSION

This paper investigates the optimization of path loss model using least square method. The outdoor measurements was taken in Nablus city, which is an urban area with geographical and frequency shortage limitations. The tuning has been conducted to make a path loss comparison with the existing models. Results from the analysis and measurements reported her lead to the conclusion that the performance of the tuned Bertoni-Walfisch model is the best among the tested ones. Fine tuning of the Bertoni-Walfisch model and Standard Macrocell model are carried out using Linear Least Square method on large number of measurement records. The mean Error value for BS 1 has been reduced to zero and the standard deviation values were reduced by 13.15% and 4.2% for Bertoni-Walfisch model and Standard Macrocell model respectively. Hence, this tuned Bertoni-Walfisch propagation model is proposed to improve the performance and so it may be used for propagation prediction in the city.

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